

In the Claims:

1. (Currently amended) A medical device comprising:

a flexible shaft comprising a pulling member movable therein, the flexible shaft having sufficient flexibility to be formed into an operable, looped configuration during use;

an actuating mechanism operatively associated with a proximal end of the flexible shaft;

an end effector associated with the distal end of the flexible shaft, wherein the end effector is operatively associated with a distal end of the pulling member; ~~and~~

wherein the actuator mechanism has a first configuration in which the actuator mechanism is decoupled from the pulling member, and a second configuration wherein the actuator mechanism becomes operatively coupled to the pulling member to operate the end effector;

wherein the actuator mechanism comprises an actuator movable from a first position wherein the actuator mechanism is decoupled from the pulling member to a second member wherein the actuator mechanism becomes operatively coupled to the pulling member; wherein the actuator is movable from the first position to the second position by squeezing with a single hand

wherein the actuator is movable from the second position to a third position wherein the end effector is operated; and

wherein the actuator is movable from the first position to the second position by squeezing with a single hand.

2. (canceled).

3. (canceled).

4. (original) The device of Claim 1 wherein the actuating mechanism comprises a resilient member for operatively coupling the actuation member to the pulling member.

5. (original) The device of Claim 4 wherein the resilient member comprises a spring.

6. (original) The device of Claim 5 wherein the resilient member comprises a torsion spring.

7. (canceled).

8. (original) The device of Claim 1 wherein a proximal end of the pulling member is joined to a relatively larger diameter member, and wherein the actuator mechanism engages the relatively larger diameter member to provide coupling of the actuator mechanism to the pulling member.

9. (original) The device of Claim 8 wherein the actuator mechanism engages the relatively larger diameter member by gripping engagement.

10. (original) The device of Claim 8 wherein the gripping engagement is provided by a resilient member.

11. (original) The device of Claim 10 wherein the resilient member comprises a torsion spring.

12. (original) The device of Claim 1 wherein the end effector is selected from the group consisting of a biopsy

forceps, grasping forceps, surgical scissors, extractors, and snares.

13-15 (Canceled)